

## NSDE 1: LECTURE 8

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$$u' = f(t, u), \quad u(t_0) = u_0.$$

The general form of a linear multistep method is

$$\sum_{j=0}^k \alpha_j U_{n+j} = h \sum_{j=0}^k \beta_j f(t_{n+j}, U_{n+j})$$

A method is zero-stable if there exists a constant  $K$  such that, for any two sequences  $U_0, U_1, \dots, U_{k-1}$ , and  $\hat{U}_0, \hat{U}_1, \dots, \hat{U}_{k-1}$ ,

$$|U_n - \hat{U}_n| \leq K \max\{|U_0 - \hat{U}_0|, |U_1 - \hat{U}_1|, \dots, |U_{k-1} - \hat{U}_{k-1}|\}$$

for  $t_n \leq T_M$  and as  $h \rightarrow 0$ .

The first characteristic polynomial is given by

$$\rho(z) = \sum_{j=0}^k \alpha_j z^j$$

The second characteristic polynomial is given by

$$\sigma(z) = \sum_{j=0}^k \beta_j z^j$$

### Theorem (Root condition)

A linear multistep method is zero stable for any ODE

$$u' = f(t, u)$$

where  $f$  obeys a Lipschitz condition if and only if all zeros of its first characteristic polynomial lie inside the closed unit disk, with any that lie on the unit circle being simple.

### Lemma

Consider the  $k$ th order homogeneous linear recurrence relation

$$\alpha_k y_{n+k} + \dots + \alpha_1 y_{n+1} + \alpha_0 y_n = 0, \quad n = 0, 1, 2, \dots$$

with  $\alpha_k \neq 0$ ,  $\alpha_0 \neq 0$ ,  $\alpha_j \in \mathbb{R}$ ,  $j = 1, \dots, k$ , and the corresponding characteristic polynomial:

$$\rho(z) = \alpha_k z^k + \dots + \alpha_1 z + \alpha_0.$$

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Let  $z_r$ ,  $1 \leq r \leq l$ ,  $l \leq k$ , be distinct roots of the polynomial  $\rho$ , and let  $m_r \geq 1$  denote the multiplicity of  $z_r$ , with  $m_1 + \cdots + m_l = k$ .

If a sequence  $(y_n)$  of complex numbers satisfies the recurrence relation above, then

$$y_n = \sum_{r=1}^l p_r(n) z_r^n \quad \forall n \geq 0,$$

where  $p_r(\cdot)$  is a polynomial in  $n$  of degree  $m_r - 1$ ,  $1 \leq r \leq l$ . In particular, if all roots are simple, (i.e.  $m_r = 1$ ,  $1 \leq r \leq k$ ), then the  $p_r$  are constants.

(See, e.g, Suli and Mayers (Lemma 12.1) for a sketch of the proof)

**Proof of Root condition (necessity)**

We want to prove that zero-stability implies the root condition. Suppose that

$$\sum_{j=0}^k \alpha_j U_{n+j} = h \sum_{j=0}^k \beta_j f(t_{n+j}, U_{n+j})$$

is zero stable. Then applying the method to the ODE  $u' = 0$ ,  $u(0) = 0$  gives

$$\alpha_k U_{n+k} + \alpha_{k-1} U_{n+k-1} + \cdots + \alpha_1 U_{n+1} + \alpha_0 U_n = 0$$

This is a difference equation, and from the lemma, it's general solution is of the form

$$U_n = \sum_s p_s(n) z_s^n,$$

where  $z_s$  is a zero of

$$\rho(z) = \sum_{j=0}^k \alpha_j z^j$$

of multiplicity  $m_s \geq 1$  and  $p_s$  is a polynomial of degree  $m_s - 1$ .

If  $|z_s| > 1$  for some  $s$  then there are starting values such that the solution grows like  $|z_s|^n$ .

If  $|z_s| = 1$  and  $z_s$  has multiplicity  $m_s > 1$ , then there are starting values such that the solution grows like  $n^{m_s-1}$ . In either case, there are solutions which grow unbounded as  $n \rightarrow \infty$ ,  $h \rightarrow 0$ ,  $nh$  fixed.

Consider starting data  $U_0, U_1, \dots, U_{k-1}$  that gives such an unbounded solution, and the starting data

$$\hat{U}_0, \hat{U}_1 = \cdots = \hat{U}_{k-1} = 0,$$

which gives  $\hat{U}_n = 0$  for all  $n \geq 0$ .

Therefore, if a method violates the root condition, it cannot be zero stable.

The proof of the converse is technical, and outside the scope of this course.

**Example**

Simpson rule method:

$$U_{n+2} - U_n = \frac{h}{3}(f_{n+2} + 4f_{n+1} + f_n)$$

$$\rho(z) = z^2 - 1$$

$$z = \pm 1$$

(where  $f_n = f(t_n, U_n)$ ).

Simple roots on the unit circle, so the method is zero-stable.

**Example**

Adams-Bashforth method

$$U_{n+4} - U_{n+3} = \frac{h}{24}(-9f_n + 37f_{n+1} - 59f_{n+2} + 55f_{n+3})$$

$$\rho(z) = z^4 - z^3 = z^3(z - 1)$$

$$z_1 = z_2 = z_3 = 0, z_4 = 1$$

**Example** A 3-step 6-th order accurate method:

$$11U_{n+3} + 27U_{n+2} - 27U_{n+1} - 11U_n = 3h(f_{n+3} + 9f_{n+2} + 9f_{n+1} + f_n)$$

$$\rho(z) = 11z^3 + 27z^2 - 27z - 11$$

$$z_1 = 1, z_2 \approx -0.3189, z_3 \approx -3.1356$$

since  $|z_3| > 1$ , the method is not zero stable.

**Convergence**

The linear multistep method is said to be *convergent* if, for all initial value problems  $u' = f(t, u)$ ,  $u(t_0) = u_0$  (which satisfies the assumptions of Picard's theorem),

$$\lim_{h \rightarrow 0, nh=t-t_0} U_n = u(t)$$

for all  $t \in [t_0, T_M]$  and for all solutions  $\{U_n\}_{n=0}^N$  with consistent starting condition, i.e., with starting values

$$U_s = \eta_s(h)$$

for which  $\lim_{h \rightarrow 0} \eta_s(h) = U_0$ ,  $s = 0, 1, \dots, k - 1$ .

Convergence is a vital property of a numerical method. It tells us that, if we take smaller and smaller time steps, we will get better and better approximations to the true solution.